How to define Newton trajectories for mechano-chemistry

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Catch bonds | Newton trajectories | Potential energy surface

 We congratulate C.O.Barkan and R.F.Bruinsma (1) for adapting potential energy surfaces (PES) for selectins
 (Fig. 1). This letter concerns mathematical inaccuracies. One treats the mechanochemical potential

$$V_f(\mathbf{x}) = V(\mathbf{x}) - f \ l \cdot \mathbf{x}$$

V(.) is the PES, l is the direction of an external force, f its magnitude. The stationary points \mathbf{x}_c of the PES move under the force. Barkan and Bruinsma develop with (2) a differential equation

$$rac{d\mathbf{x}_c}{df} = H^{-1}(\mathbf{x}_c) \, l \; ,$$

¹¹ $H^{-1}(\mathbf{x})$ is the inverse Hessian of $V(\mathbf{x})$. We argue that use of ¹² Eq. [2] should be avoided because on a path from a minimum ¹³ to a saddle points (SP) it is Det(H) > 0 in the minimum and ¹⁴ negative in the SP. So there is always a point on the path ¹⁵ where Det(H)=0 and where Eq.[2] becomes singular because ¹⁶ the inverse matrix is used. This problem was solved by Branin ¹⁷ (3). The better equation is with (4)

$$\frac{d\mathbf{x}_c}{dt} = Det(H) \ H^{-1}(\mathbf{x}_c) \ grad(\mathbf{x}_c) \ .$$
[3]

¹⁹ $grad(\mathbf{x})$ is the gradient of $V(\mathbf{x})$. So the right one desingularized ²⁰ Eq.[3] is made worse into an equation with a singularity [2]. ²¹ The solutions of Branins Eq.[3] are called Newton trajectories ²² (NT), for more than a third of a century (4–6).

Singularities of [2] are artificial. They do not generate a force-induced switch (1). Every solution of Eq. [3] to different directions l connects a minimum with an SP and crosses the curve where Det(H) = 0 applies (green) called bond breaking point (7–9).

What is the field for NTs? In Fig. 1 we draw a family of 28 NTs (blue). They follow the gradient field of the PES of 29 Eq. [3], however not the field [2] with l=(1,1). The 'flow' image 30 in Fig. 1D in (1) uses Eq. [2]. This picture is misleading for the 31 idea of NTs. The arrow field in this Fig. 1D asserts a general 32 33 meaning of the vectors of Eq. [2] in the full configuration space. This is not correct. In Fig. 1 we insert a trajectory of Eq. [2] 34 (magenta) with start in the magenta point, with l=(1,1). It 35 is not an NT because it does not cross a stationary state, \mathbf{x}_{c} . 36 The magenta curve demonstrates well the circular character 37 of the field [2], however, it has nothing to do with the solution 38 of our problem: the movement of stationary points of the PES 39 under an external force. The direction l=(1,1) only applies to 40 the bold NT of Fig. 1. Apart from this NT this direction is 41

of no interest. Drawing a vector field like in Fig. 1D of (1) is possible, but its solution curves are useless for our problem. NTs are not 'elliptic' like claimed in (1).

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NTs can have turning points (blue dots). One could use the first appearance of a TP as an indication of a possible switch from slip- to catch-bond character, see the magenta dot. NTs without a TP on their energy profile are slip bonds (6), however, a TP is not sufficient for catch bonding, see an extreme counterexample (4). So the *l*-switch points and switch-lines in (1) are not well justified (10).

NTs offer tools for the investigation of reaction path models. We request the use of Branins Eq.[3] for the treatment of mechano-chemistry.

We used Mathematica 13.3.1.0 for Linux x86(64-bit).

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Fig. 1. PES of L-selectin (1) with \mathbf{x} =(L, d) [nm], and NTs. R: minimum, thin black: level lines, thick blue: NT to direction (1,1), blue: other NTs, green: Det(H)=0 line, TPs: blue dots, magenta squiggle: trajectory to [2] through magenta dot.

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